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E SOFTWARE
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HEIDENHAIN

Empowered Encoder for Smarter Condition Monitoring

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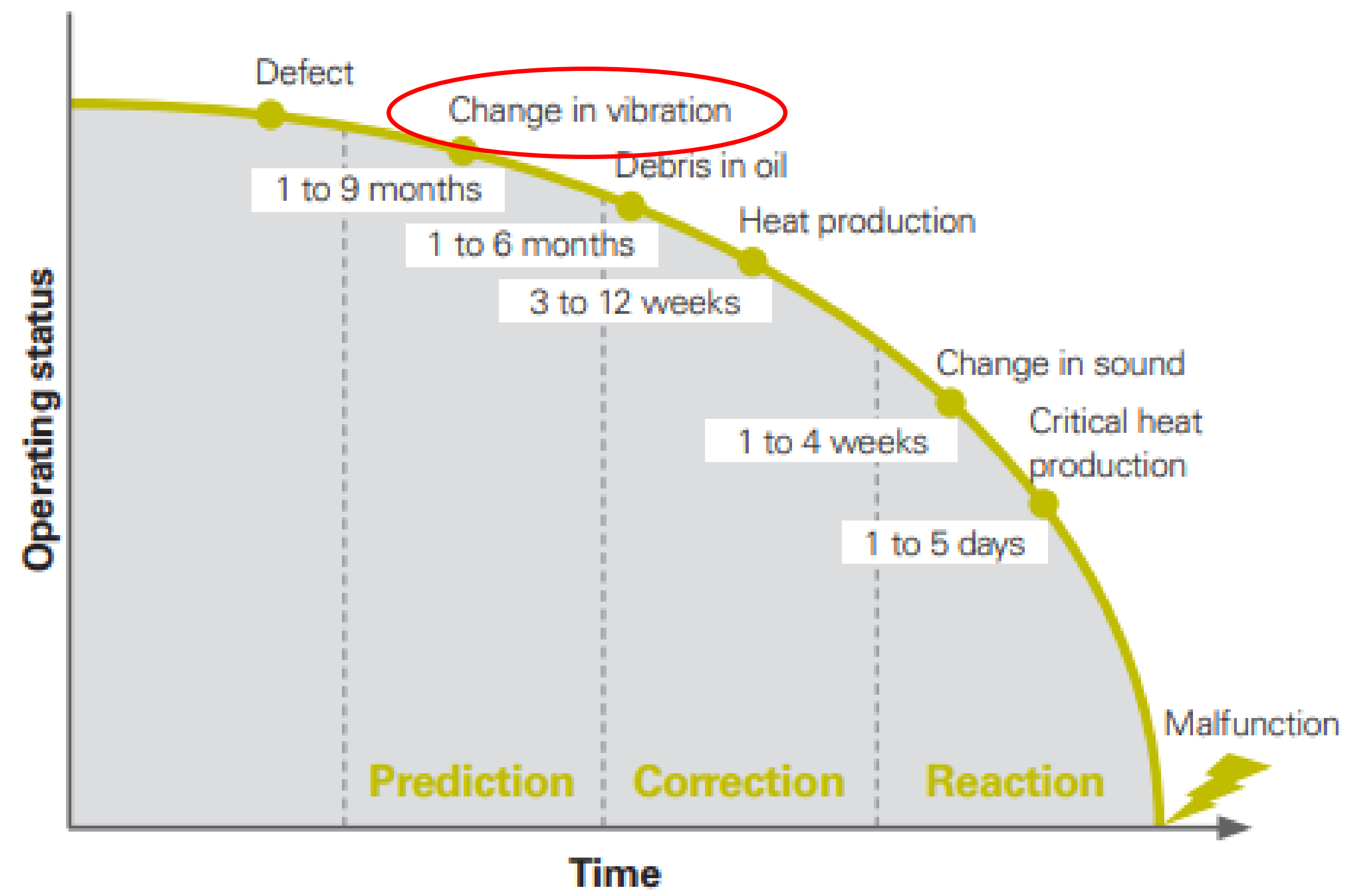


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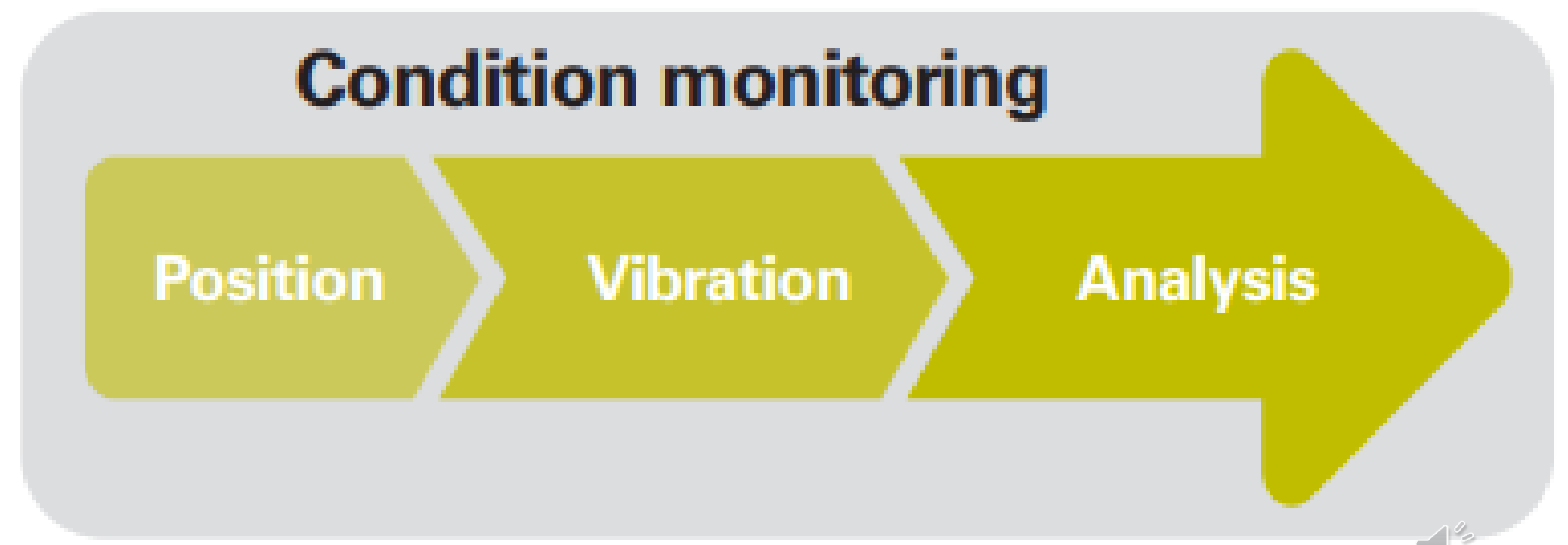
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Motivation: Condition monitoring of rotating axes



The online condition monitoring of rotating machine elements enables:

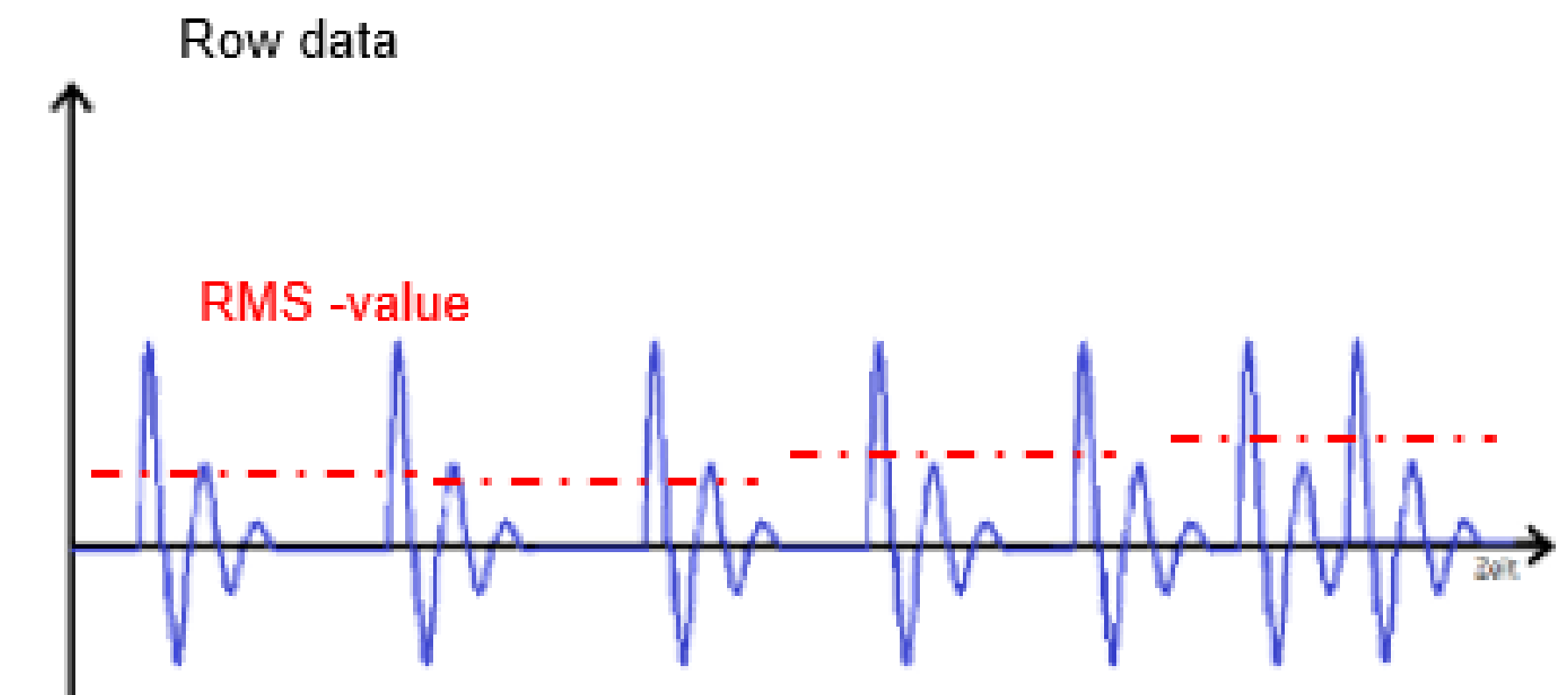
- Minimal downtime
- Higher productivity
- Early detection of damage
- Exact failure analysis
- Reduction of servicing intervals
- Maintenance planning
- Remaining service life estimation



Evaluating acceleration signals

Vibration characteristic value RMS

- An increase in the vibration characteristic value RMS indicates the wear of a component in the machine
- Benefits:
 - Simple statement about actual status
 - Easy to calculate
- Disadvantages:
 - Which component shows the wear/damage?
 - Susceptible to sturgeon
 - Limited informative value

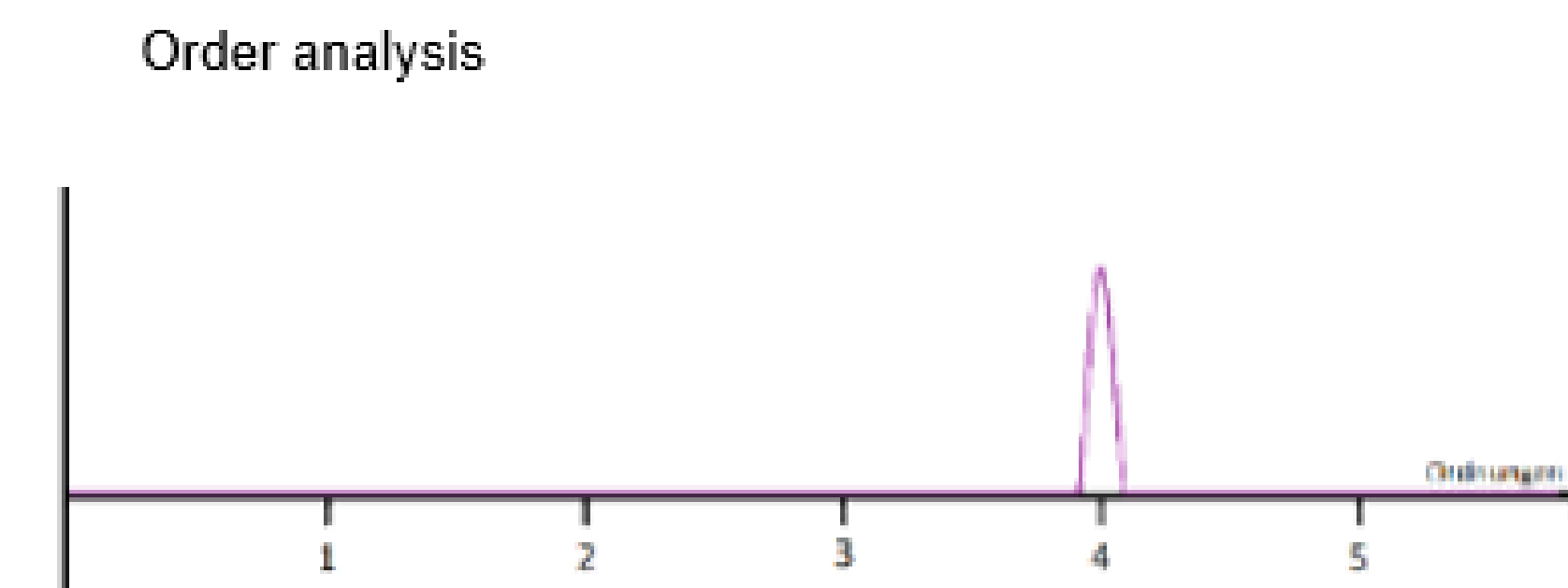
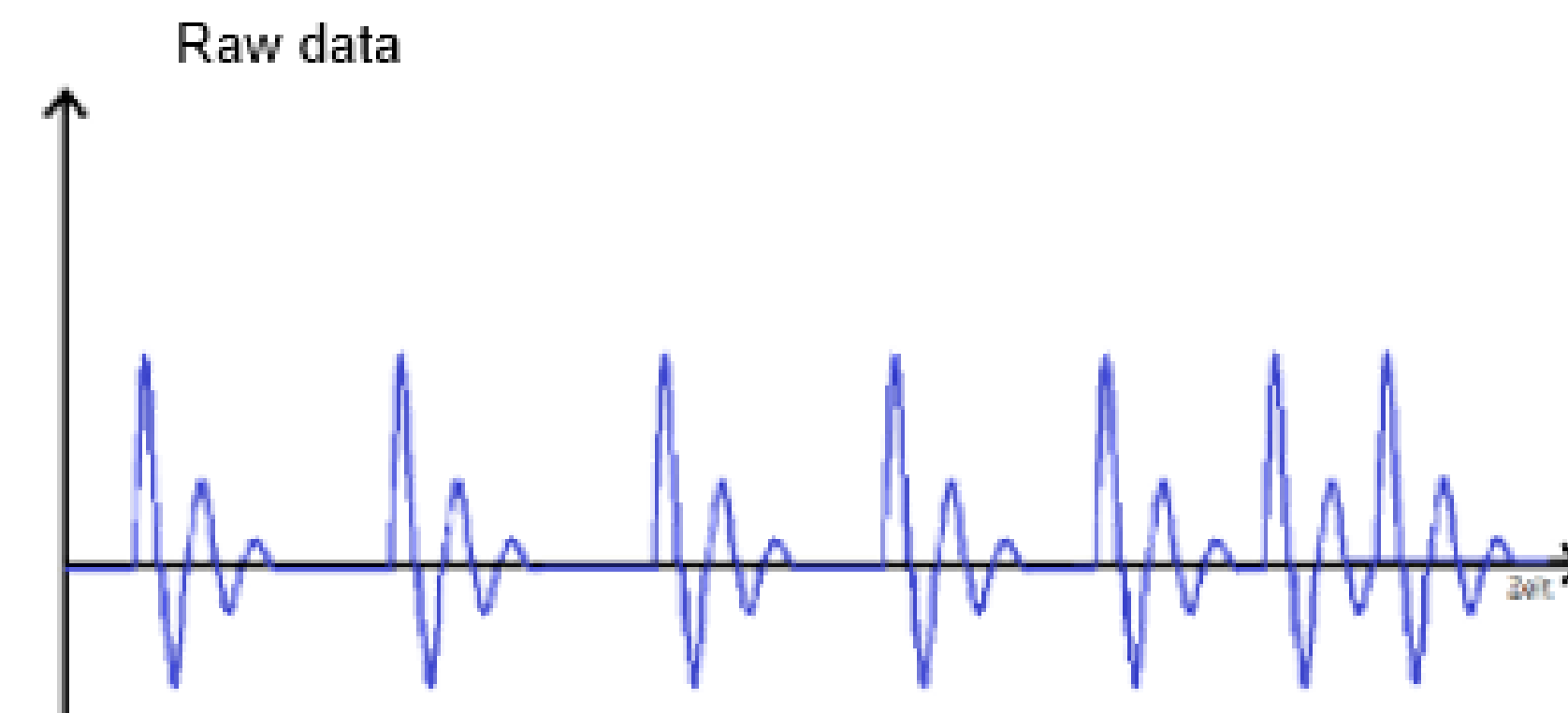


$$RMS = \sqrt{\frac{1}{n} \sum_i x_i^2}$$

Evaluating acceleration signals

Order analysis

- The order of each individual component (e.g. each individual part of a ball bearing) is known (manufacturer information)
- Benefits:
 - Identification of the defective component (e.g. outer ring of a ball bearing)
 - Analysis method with maximum sensitivity
 - Early detection of faults
 - Immune to external interference
 - Continuous monitoring in normal operation (varying speed)
- Disadvantages:
 - Vibration signals synchronised with the angle of rotation required



periodisches, stoßförmiges Ereignis



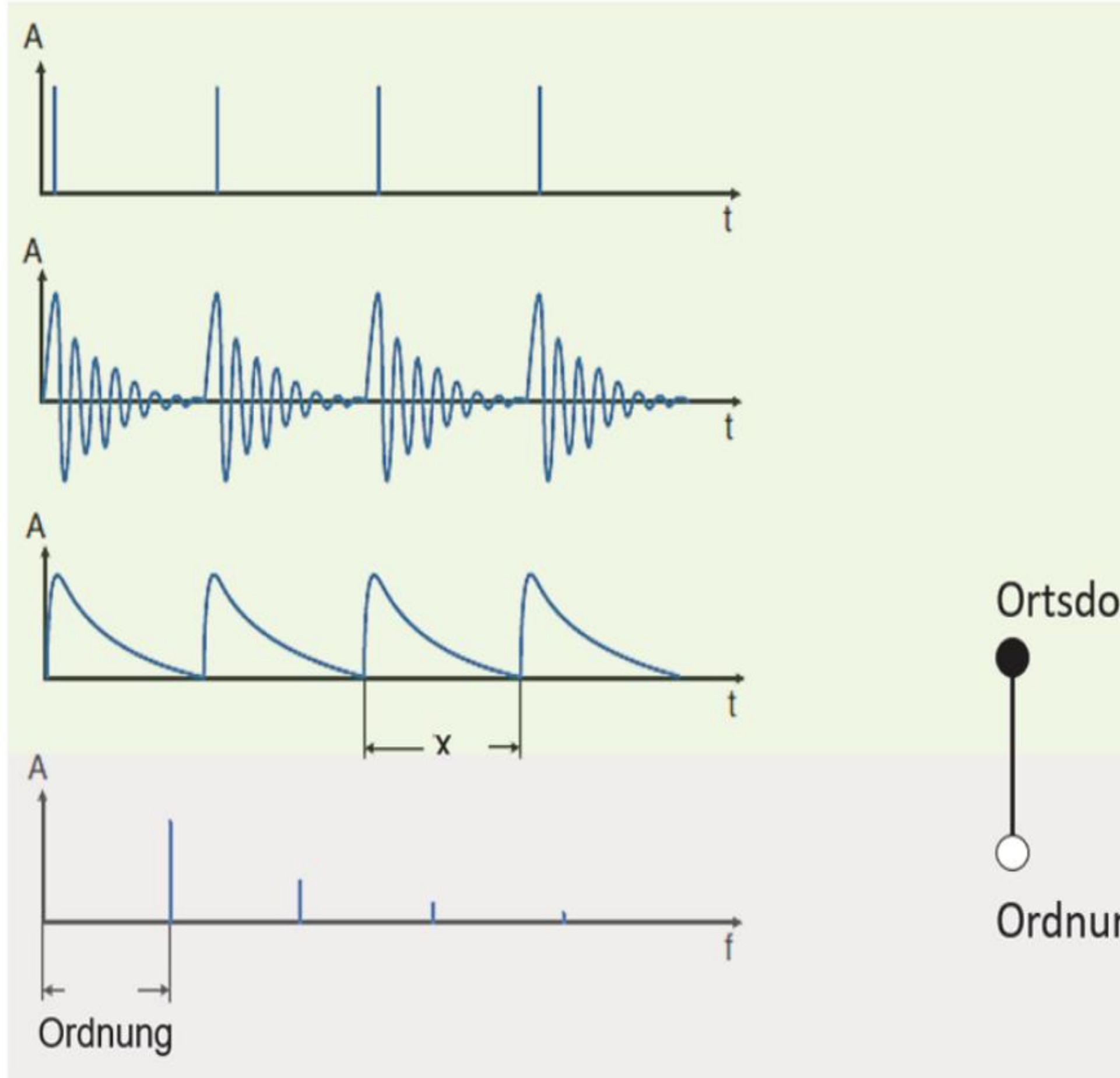
Reaktion der Struktur (Körperschall)



Bildung der Hüllkurve



Hüllkurvenspektrum

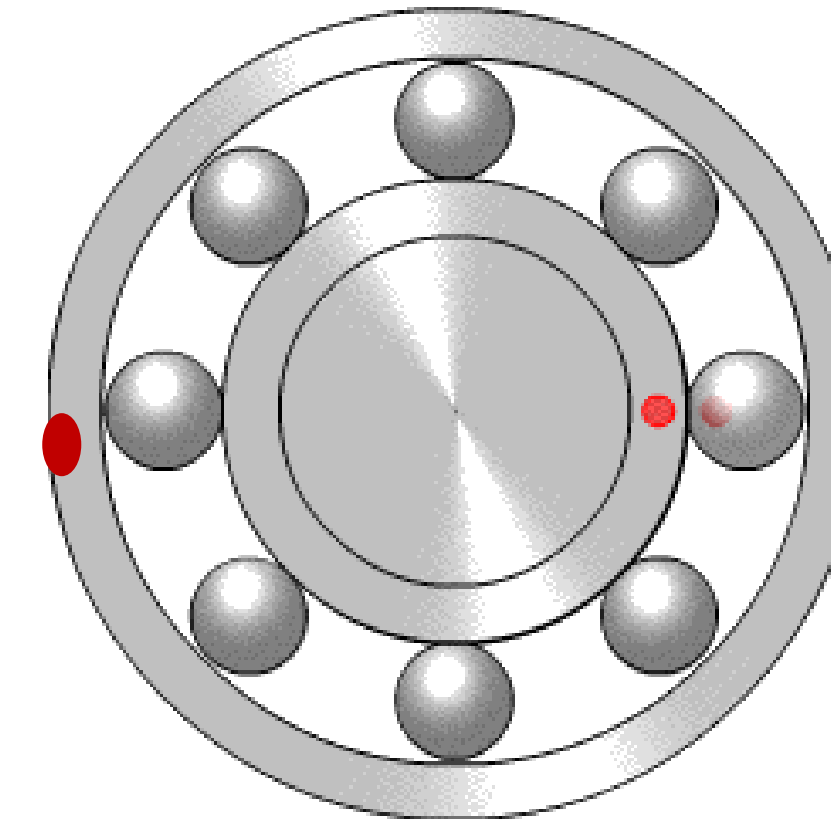


Quelle: Maschinenelemente 2, Berthold Schlecht

Ortsdomäne



Ordnungsdomäne



● Damage

bearing frequency				
Rolling element t & cage	Rolling element about its axis	Point on outer ring	Rolling element	Point on inner ring
0,398	2,339	3,578	4,677	5,422

Measurement - Display



Measurement - Display

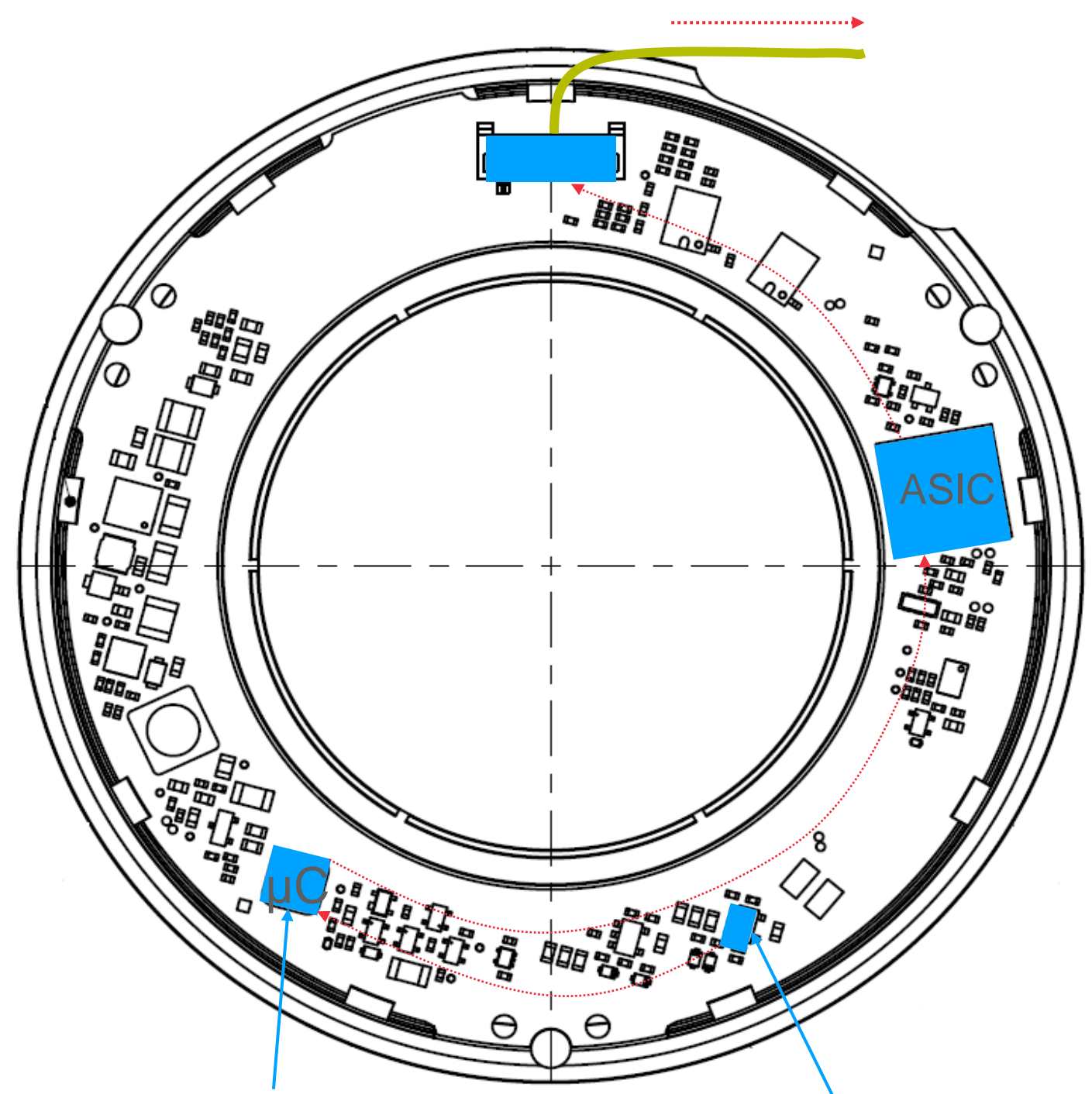


Measurement - Display



Significant amplitude change can be seen in the order of the outer ring!

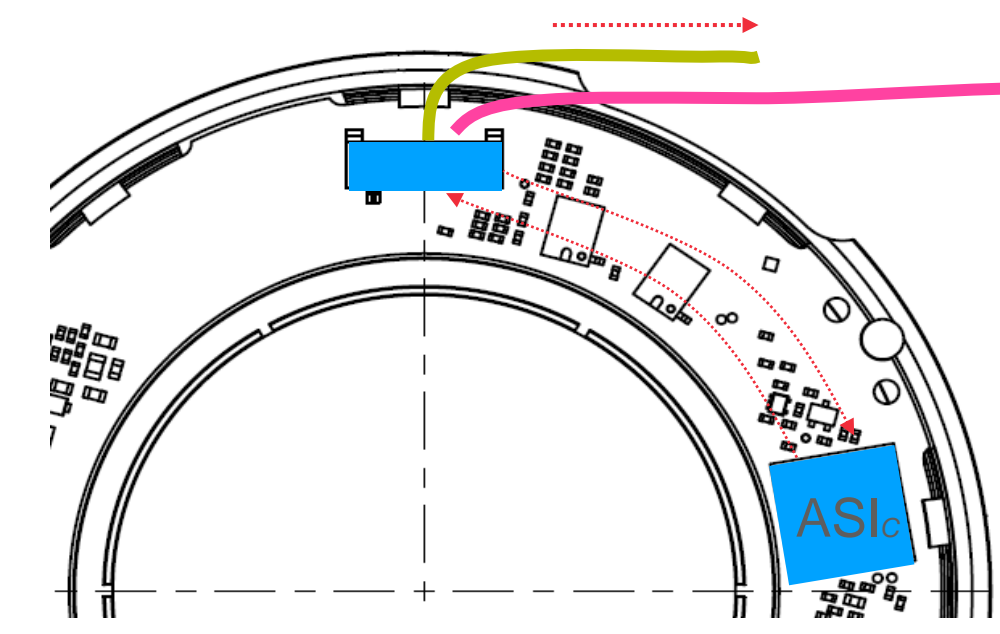
Showing the measured values of an undamaged ball bearing as a reference (see blue curve)



Data processing e.g. order analysis

Acceleration sensor

■ Integrate external sensor into interface data stream

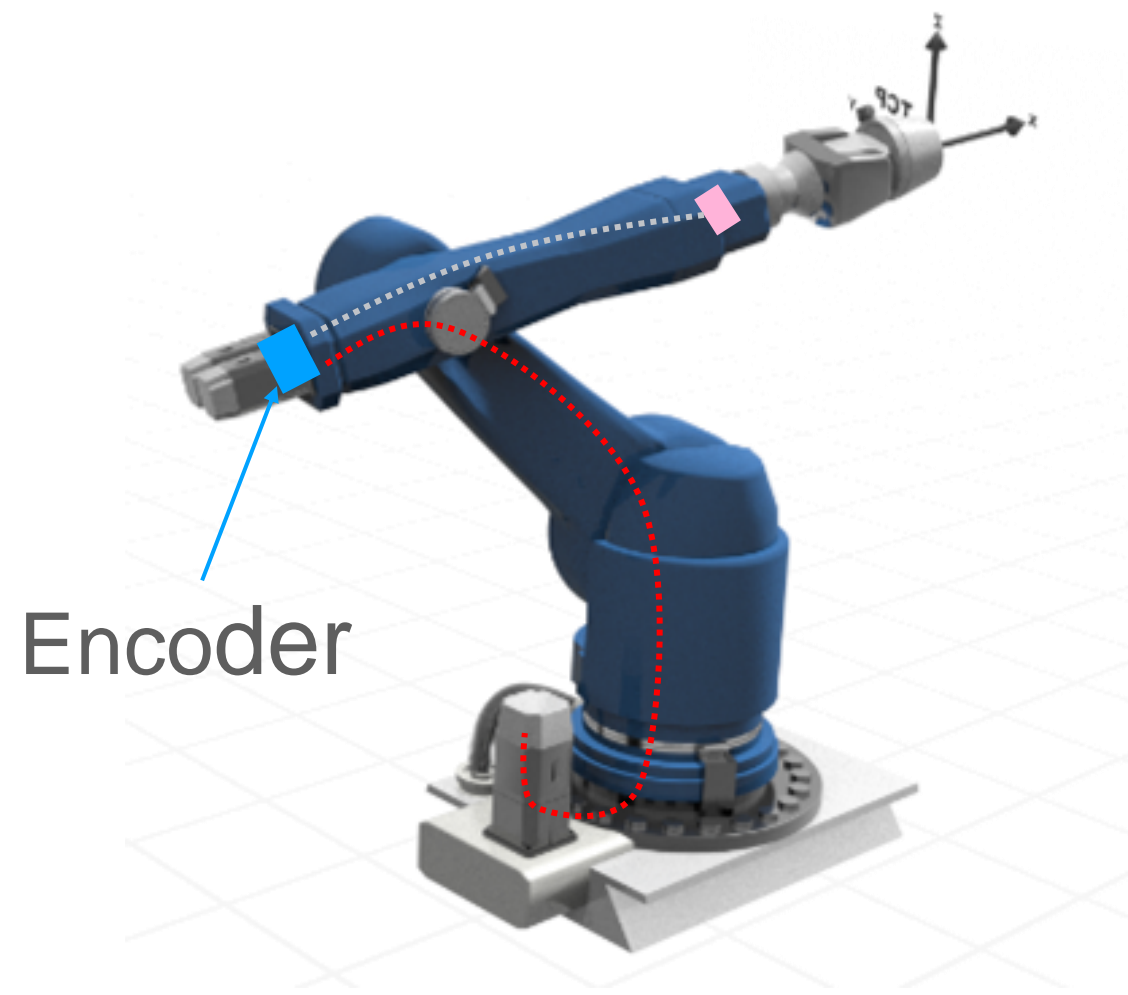


Raw data

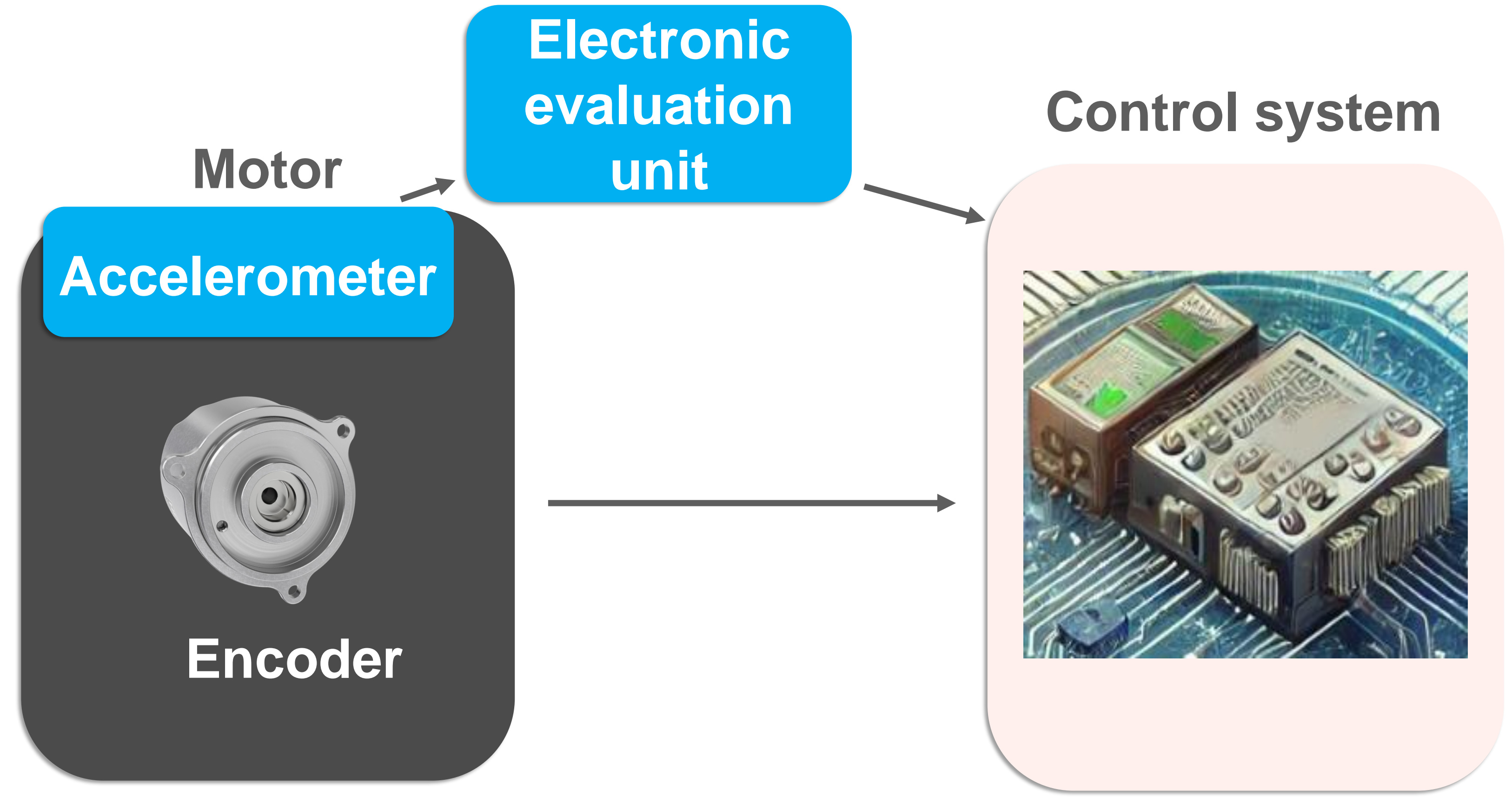
µC or FPGA

Acceleration sensor

robot axis dampening

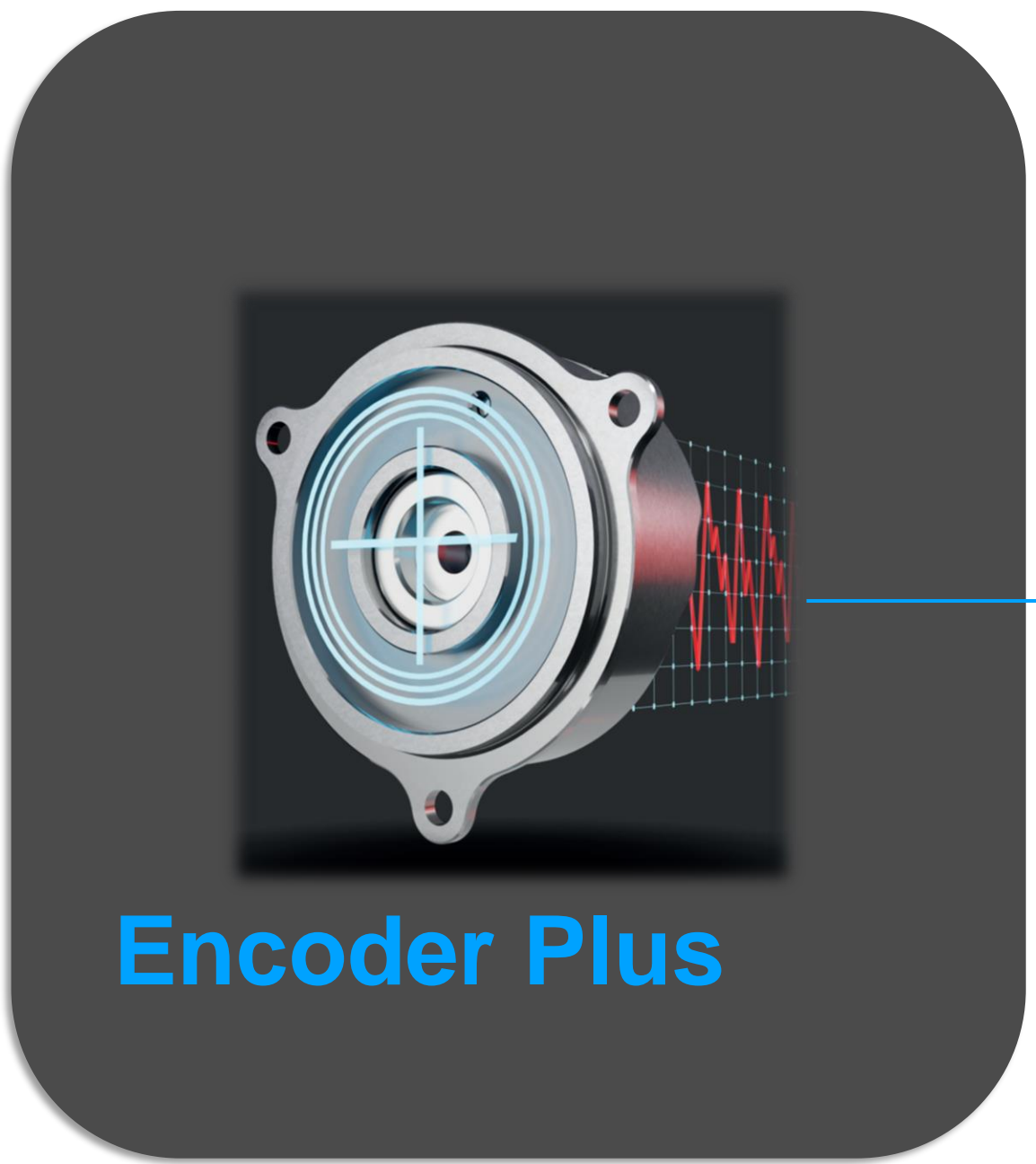


Previously: Separate accelerometer



Integrated accelerometer

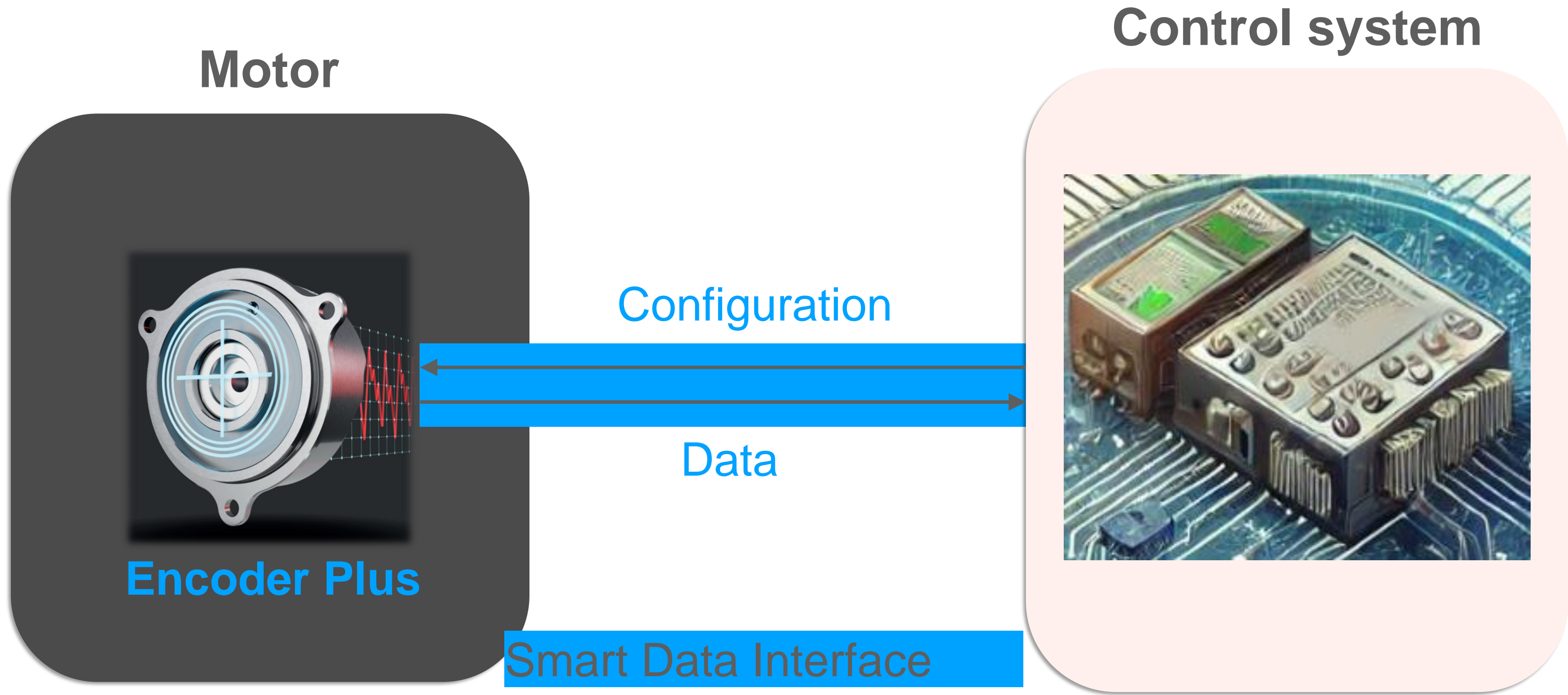
Motor



Control system



Integrated accelerometer



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Motor feedback encoder for servomotors

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Exl 13xx Plus

- Inductive scanning
- Resolution 23 bit
- Multiturn option 12 bit
- Interface EnDat 3



- Integrated 3D MEMS accelerometer
- Vibration analysis

Prototypes available

Technical data

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Accelerometer	
Measuring range	$\pm 15 \text{ g}$, $\pm 30 \text{ g}$, $\pm 60 \text{ g}$
Measuring step	16 bit
Bandwidth	bis 8000 Hz
Number of axes	3
Evaluation (configurable)	
Characteristic value	RMS
Vibration analysis	Order and frequency analysis <ul style="list-style-type: none">- Envelope analysis and bandpass filter- Fast Fourier transformation- Monitoring function: 256 values- Speed trigger